Polynomial-Time Algorithms for Contiguous Art Gallery and Related Problems

Ahmad Biniaz, Anil Maheshwari, Magnus Christian Ring Merrild, Joseph S.B. Mitchell, Saeed Odak, Valentin Polishchuk, Eliot W. Robson, Casper Moldrup Rysgaard, Jens Kristian Refsgaard Schou, Thomas Shermer, Jack Spalding-Jamieson, Rolf Svenning, Da Wei Zheng

The Contiguous Art Gallery Problem is Solvable in Polynomial Time,

- Merrild, Rysgaard, Schou & Svenning

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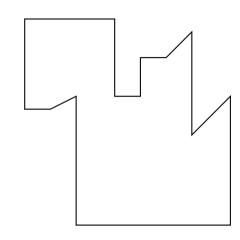
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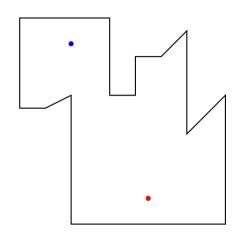
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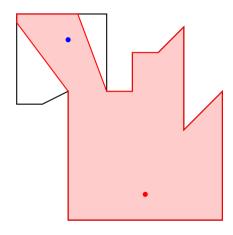
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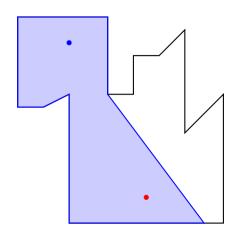
The Analytic Arc Cover Problem and its Applications to Contiguous Art Gallery, Polygon Separation, and Shape Carving

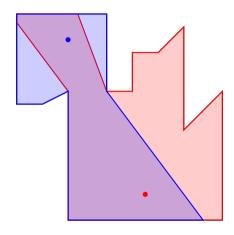
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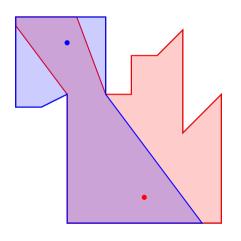






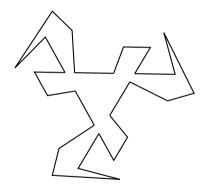


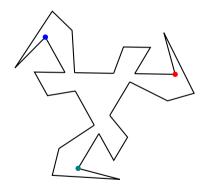


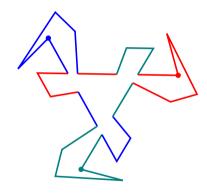


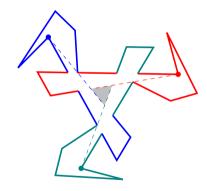
 $\exists \mathbb{R}$ -complete

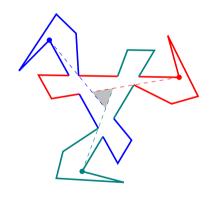
[Abrahamsen, Adamaszek Miltzow, 2021]



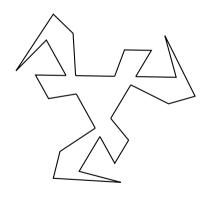




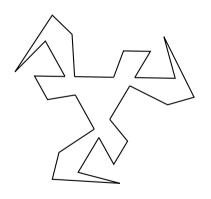




 $\exists \mathbb{R}$ -complete [Stade, SoCG25]



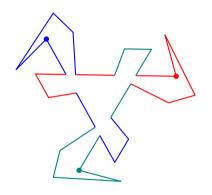
Goal: Guard boundary (few guards)



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Restriction:

Guards assigned to contiguous parts of boundary

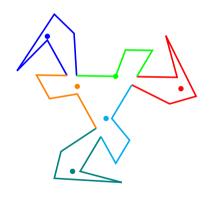


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(Not allowed)



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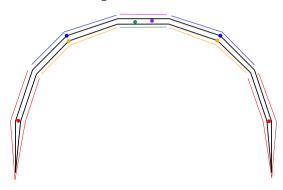
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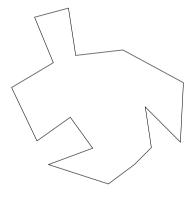
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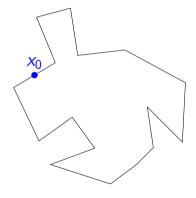
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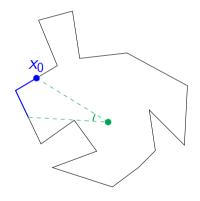
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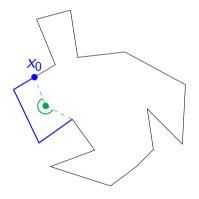
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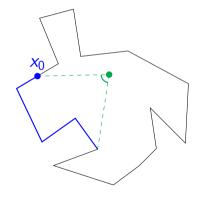


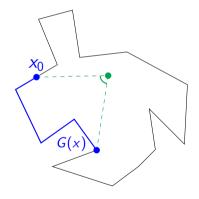


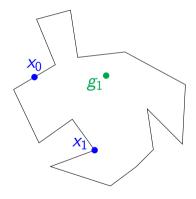


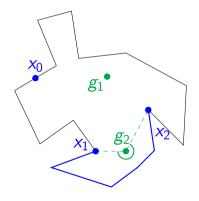


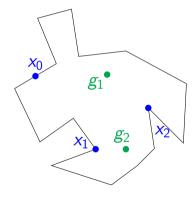


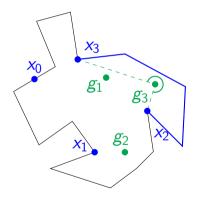


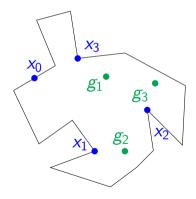




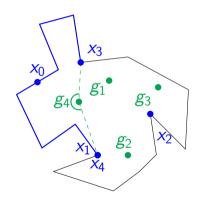








"Take greedy steps"



One revolution: $\mathcal{O}(n^2 \log(n))$ time.

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Guard count: **OPT** or **OPT+1**, depending on starting point.

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Exact solution attainable?

Theorem (Main theorem)

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Common element: Greedy steps

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► Method 1: Perform more greedy steps

Three different algorithms/methods

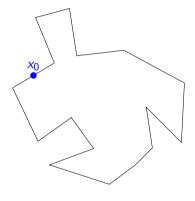
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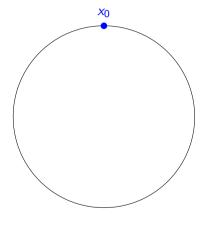
- ► Method 1: Perform more greedy steps
- ► Method 2: Select good candidate starting points

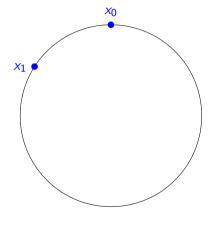
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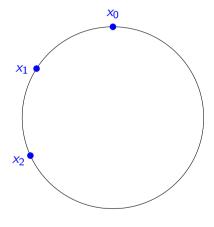
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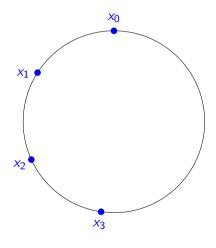
- ▶ Method 1: Perform more greedy steps
- Method 2: Select good candidate starting points
- ▶ Method 3: Try every starting point simultaneously

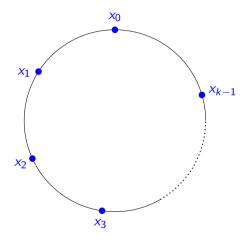


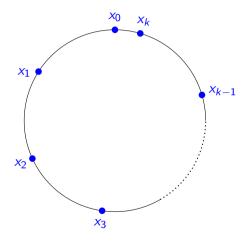


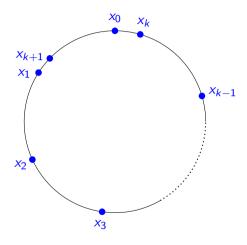


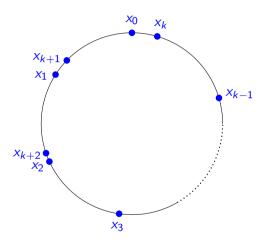


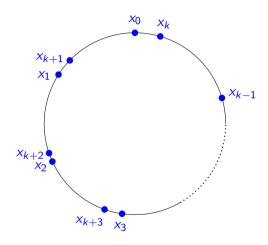


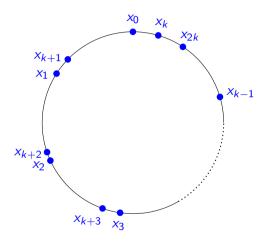


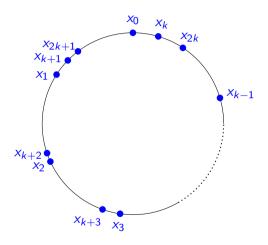


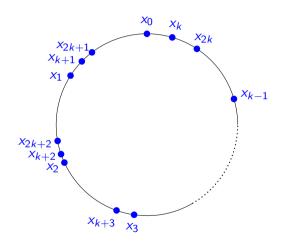


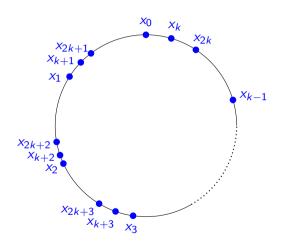


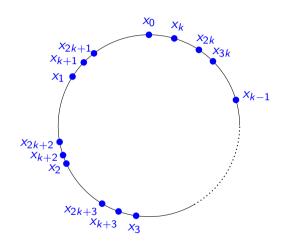


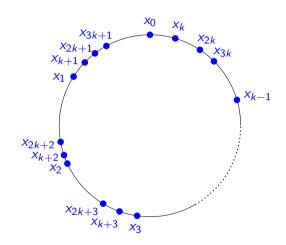


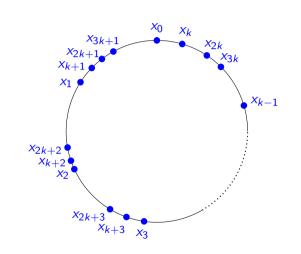


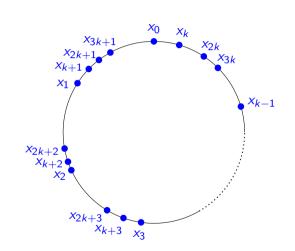


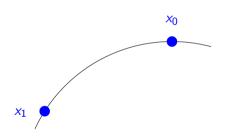


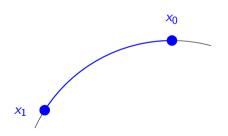


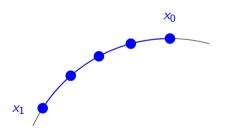


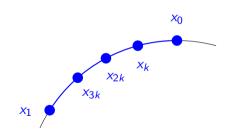




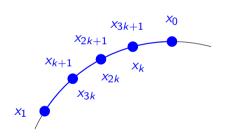




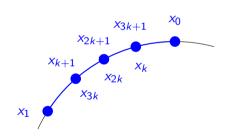




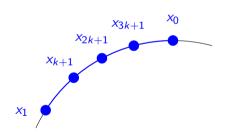
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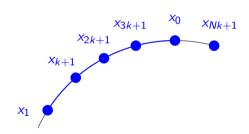
- 1. Repetition
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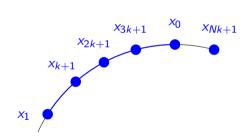
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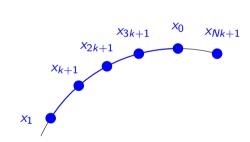


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- 3. $x_{k+1}, x_{2k+1}, x_{3k+1}, \ldots$ pass x_0



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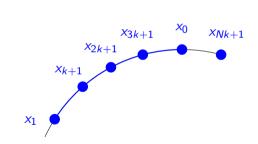
Guaranteed in $\mathcal{O}(n^3 \mathbf{OPT})$ revolutions.

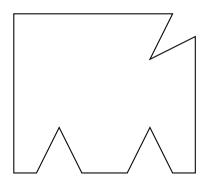


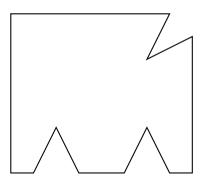
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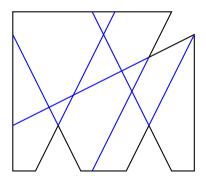
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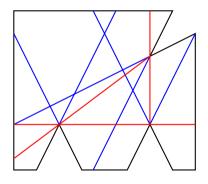
 $\mathcal{O}(n^5 \mathbf{OPT} \log n)$ runtime.

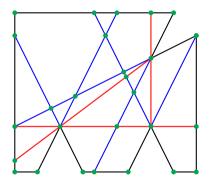


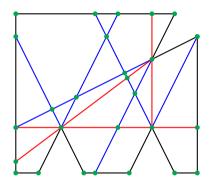






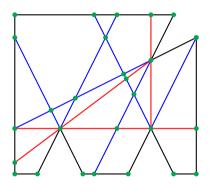






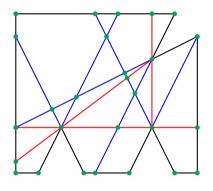
Shows existance of optimal solutions, with at least one guard at an <u>incidence</u> <u>point</u>.

At most $\mathcal{O}(n^3)$ incidence points.



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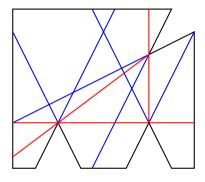
At most $\mathcal{O}(n^3)$ incidence points. Try them all!

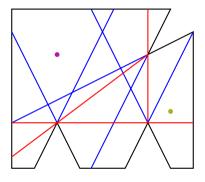


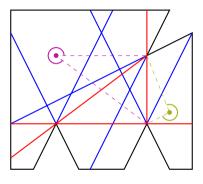
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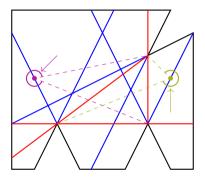
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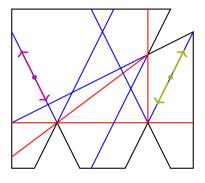
Total running time: $\mathcal{O}(n^6 \log(n))$.

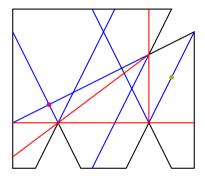










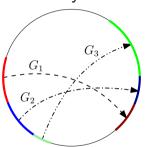


Method 3: Closed-Form Analysis ("Analytic Arc Cover Framework")

Idea: Find a closed form expression of greedy step ${\it G}$ to evaluate every starting point simultaneously.

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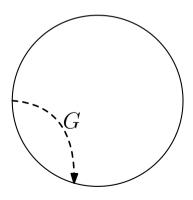
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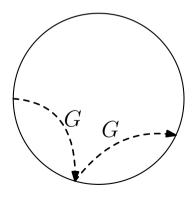
$$G_1 = \frac{ax+b}{Cx+d}, \ G_2 = \frac{a'x+b'}{C'x+d'}, \ G_3 = \frac{a''x+b''}{C''x+d''}, \dots$$

Bounds: $[a_0 + b_0\sqrt{c_0}, a_1 + b_1\sqrt{c_1}), [a_1 + b_1\sqrt{c_1}, a_2 + b_2\sqrt{c_2}), [a_2 + b_2\sqrt{c_2}, a_3 + b_3\sqrt{c_3}), \dots$

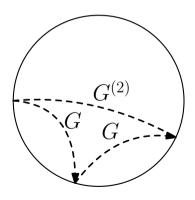
Input: Closed form expression for *G*



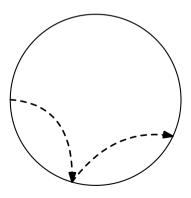
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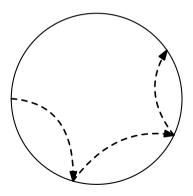
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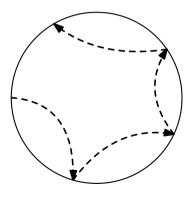
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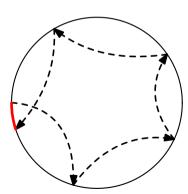
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Algorithm: Repeatedly compose G with itself... until $G^{(k)}$ exceeds a full loop somewhere.

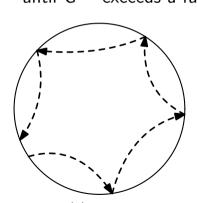
Output: k



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Need to test $G^{(k)}$ everywhere at once.

Analytic Arc Cover Framework: Benefits

▶ Only need to find one function

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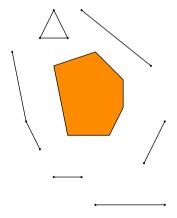
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- ► Robust to some problem variants

Analytic Arc Cover Framework: Benefits

- ► Only need to find one function
- ► Robust to some problem variants
- ► Also applicable to some other problems. . .

More problems: Line Segment/Polygon Separation

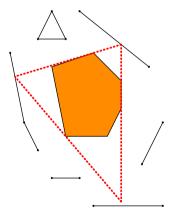
Input: A convex polygon and a set of line segments.



More problems: Line Segment/Polygon Separation

Input: A convex polygon and a set of line segments.

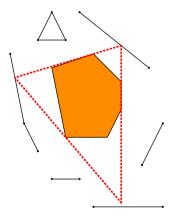
Output: A convex polygon separating the two, minimizing vertices.



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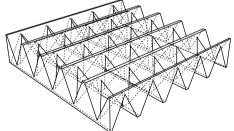
Solvable with analytic arc cover framework!

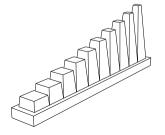
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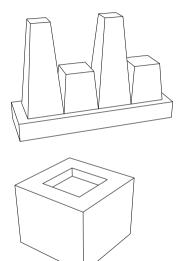
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Carveable:

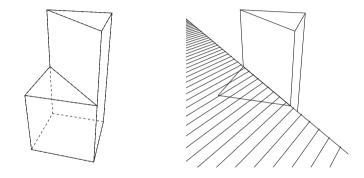






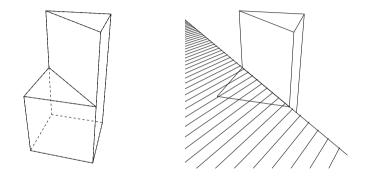


Min Half-Plane Cutting: Reducing to 2D



 $\blacktriangleright \ \ \mathsf{Minimizing} \ \mathsf{in} \ \mathsf{3D} \to \mathsf{Minimizing} \ \mathsf{(many)} \ \mathsf{in} \ \mathsf{2D}$

Min Half-Plane Cutting: Reducing to 2D



- ightharpoonup Minimizing (many) in 2D
- ► Reduction to line segment/polygon separation

Faster runtime:

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Other variants:

- ► Higher dimensional galleries.
- Each guard guards at most *m* polygonal arcs.

Thank you ¹

¹Also Jack is looking for PhD positions...